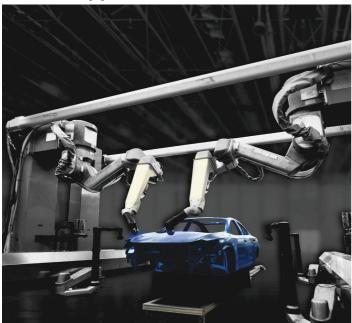
FANUC Robot P-1000iA



Interior Application



P-1000iA Interior Door Zone With P-20iA Openers

Features

Design

- Unique Painting Robot With Seven Integrated Axes
- Optimally Position Arm In Interior & Exterior Paint Programs
- Inverted Pedestal Installation Maximizing Work Envelop
- Balanced Arm Length Provides Excellent Near & Far Reach
- Payload Supports A Range Of Rotary Atomizers & Spray Guns

Booth

- Minimizes Booth Size By Optimizing Robot Density
- In-Line Arms Maintain Process Symmetry Across The Booth

Application

- Easy Access To All Critical Process Components
- Maximized Performance With In Arm Process Components
- Integrated Fluid Delivery Systems With FANUC Servo Motors
- Direct Charge Waterborne And 1k & 2k Solventborne Systems
- 140° Hollow Wrist Optimized For Demanding Paint Processes

Controller

- A Compact And Stackable R-30iB Paint Controller
- Single Arm And Dual Arm Controller Support
- Supported By The *i*Pendant Color Graphical Teach Pendant
- Integrated Support Of Hood, Deck And Door Opener Controls
- Supports All Major Network Communications Protocols

Software Features

Paint Application

- Industry's Most Powerful & Easy-To-Use Interface PaintTool
- Integrated Diagnostic Monitoring And Reporting Of Process Parameters Provides Real-Time Strip Chart Capability

Motion Enhancement

- Software Functionality To Simplify Elbow Position Control
- Dual Check Safety Enables Smaller Booths
- Collision Guard Minimizes Application Equipment Damage

<u>Options</u>

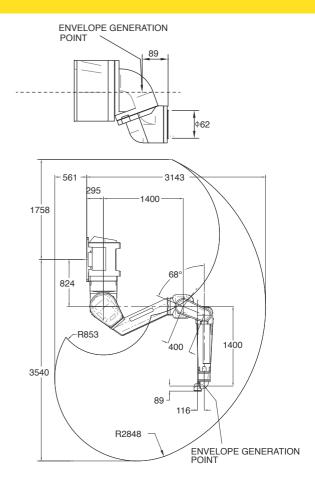
- Mechanical Unit & Paint Process Equipment Are Monitored And Protected By FANUC's Zero Down Time Package
- Pressure vs. Flow Monitoring Software Detects Fluid Delivery System Problems In Real-Time
- ROBOGUIDE PaintPRO Offline 3D Programming

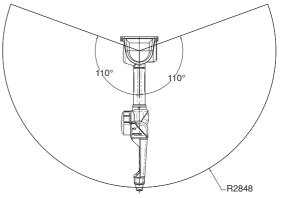
FANUC Robot P-1000iA

P-1000iA SPECIFICATIONS:

Item		Specification			
Controlled Axes		7 Axes			
	Reach	2848mm			
Motion Range * & Standard Maximum Motion Speed	J1 Axis	±110°		125° / sec	
	J2 Axis	+85° / -65°		125° / sec	
	J3 Axis	+120° / -120°		120° / sec	
	J4 Axis	+90° / -70°		120° / sec	
	J5 Axis	± 720°		200° / sec	
	J6 Axis	± 720°		200° / sec	
	J7 Axis	± 720°	2		200° / sec
Maximum Load Capacity		Maximum Tip Speed	1500m	nm/sec	1200mm/sec
		At Wrist	10	Okg 15kg	
		On J2 Arm		15kg	
		On J4 Arm		25kg	
Repeatability		± 0.5mm			
Drive Method		Electric Servo Driven AC Servo Motor			
Feedback Method		Absolute Pulse Encoders			
Axis Control		Digital-Servo Controlled Path Control Joint, Linear, And Circular Motion			
Mechanical Brakes		All Axes			
Weight		Mechanical Unit : 700kG			
Installation		Invert Mount			
Temperature Conditions		0° - 45°C			
Humidity Conditions		Normal		< 75%	
		Short Term		< 95% (< 1 month)	
		Condensat	tion No		ne Permissible
Vibration		< 0.5 m/sec ² (G)			
Hazardous Location Certifications		FMUC Class I, II, III, Div I Group C, D, E, F, G, T4 45°C Ambient			
		ATEX CE II 2 G c Ex ib px IIB T4 Ta = 0°C to +45°C			
		ATEX CE II 2 D c Ex pD 21 T135° Ta = 0°C to +45°C			

^{*} Work Envelope Generated With Identified Wrist Point Reach Measured To Faceplate Is 89mm Larger





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